PART C — 
$$(1 \times 15 = 15 \text{ marks})$$

16. (a) Using Hamming window, design an ideal High pass filter for the frequency response (15)

$$H_d(e^{j\omega}) = 1 for \frac{\pi}{4} \le |\omega| \le \pi$$

$$=0$$
 for  $|\omega| \le \frac{\pi}{4}$ 

Compute the values of n(n) for N = 11 and determine its transfer function H(z).

O

(b) Design a digital Butterworth filter to satisfy the following constraints using bilinear transformation. Assume T = 1s. (15)

$$0.9 \le \left| H(e^{j\omega}) \right| \le 1 \text{ for } 0 \le \omega \le \pi/2$$

$$\left|H(e^{j\omega})\right| \le 0.2 \text{ for } 3\pi/4 \le \omega \le \pi$$

Analyze the poles of the transfer function obtained and assess the stability of the filter.

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# Question Paper Code: 50497

## B.E./B.Tech. DEGREE EXAMINATIONS, APRIL/MAY 2023.

#### Fifth Semester

### Electronics and Communication Engineering

# EC 8553 — DISCRETE - TIME SIGNAL PROCESSING

(Common to : Biomedical Engineering / Computer and Communication Engineering / Electronics and Telecommunication Engineering / Medical Electronics)

(Regulations 2017)

Time: Three hours

Maximum: 100 marks

#### Answer ALL questions.

PART A — 
$$(10 \times 2 = 20 \text{ marks})$$

- 1. The DFT X(k) of the sequence x[n] is  $\{0,1+j,1,1-j\}$ . Find the DFT of  $y[n] = \cos\left(\frac{\pi}{2}n\right)x[n]$  using frequency shift property.
- Interpret bit reversal and in-place computation as applied to FFT.
- 3. Compare Butterworth and Chebyshev filters with respect to their magnitude response and location of poles.
- 4. What is the effect of warping on magnitude response of digital IIR filter?
- 5. A system with transfer function H(z) has impulse response h(n) defined as h(2) = 1, h(3) = -1 and h(n) = 0 otherwise. Show that H(z) is a FIR High Pass filter.
- What is the effect of having abrupt discontinuity in frequency response of FIR filters?
- 7. The filter coefficient H = -0.673 is represented by sign-magnitude fixed point arithmetic. Find the quantization error due to truncation if the word length is 6 bits.

- 8. Interpret the statement "Rounding is preferred than truncation in realizing the digital filter".
- 9. Name the functional units in a Digital Signal Processor and list their features.
- Illustrate circular buffering in DSPs with an example.

PART B 
$$-$$
 (5 × 13 = 65 marks)

- 11. (a) (i) Explain any four properties of DFT. (7)
  - (ii) Find the 8-point DFT of the sequence  $x[n] = \{0,1,2,3,4,5,6,7\}$  using Decimation in Frequency FFT algorithm. (6)

Or

- (b) (i) Explain the Radix-2 Decimation in Time FFT algorithm. (7)
  - (ii) Find the linear convolution of finite duration sequence h[n] = [1,2] and x[n] = [1,2,-1,2,3,-2,-3,-1,1,2,1] using overlap save method. (6)
- 12. (a) (i) Utilize Bilinear transformation to design a digital Chebyshev filter for the following specifications (7)

$$0.707 \le \left| H(e^{j\omega}) \right| \le 1$$
  $0 \le \omega \le 0.2\pi$   
 $\left| H(e^{j\omega}) \right| \le 0.1$   $0.5\pi \le \omega \le \pi$ 

Assume T=1 sec.

(ii) Make use of direct form I and direct form II structures to realize the system.

$$y[n] = -0.1y[n-1] + 0.2y[n-2] + 3x[n] + 3.6x[n-1] + 0.6x[n-2]$$
 (6)

Or

- (b) (i) Describe the steps to design a digital filter using the Impulse Invariance Method. (7)
  - (ii) Using impulse invariance method, determine H(z) for the analog transfer function  $H(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$ . Assume T = 1 sec. (6)

13. (a) Use frequency sampling method to determine the impulse response h(n) of a filter with N=7. The desired response is given by (13)

$$H_d(\omega) = \begin{cases} e^{-j3\omega} & 0 \le |\omega| \le \frac{\pi}{2} \\ 0 & \frac{\pi}{2} \le |\omega| \le \pi \end{cases}$$

Find the transfer function of the filter and model it using minimum number of multipliers.

Or

- (b) (i) Explain the steps in the design of linear phase FIR filters using Fourier series method. (7)
  - (ii) Model the transfer function of FIR filter  $H(z) = 1 + \frac{3}{4}z^{-1} + \frac{17}{8}z^{-2} + \frac{3}{4}z^{-3} + z^{-4} \text{ using direct form and cascade form realization.} \tag{6}$
- 14. (a) Interpret the effect of Quantization errors in computation of DFT and FFT algorithms. (13)

Or

(b) An LTI system is characterized by the difference equation y(n) = 0.95y(n-1) + x(n). Infer the limit cycle behavior and determine the dead band of the system when (13)

$$x(n) = \begin{cases} 0.875 & for \ n = 0 \\ = 0 & otherwise \end{cases}$$

Assume that the product is quantized to 4 bits (excluding sign bit) by rounding.

15. (a) With flow diagram, describe the data path and MAC unit in a DSP Processor. (13)

Or

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(b) Classify the addressing modes used in digital signal processors and explain them with examples. (13)

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