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Question Paper Code: 41413

09/05/18

B.E./B.Tech. DEGREE EXAMINATION, APRIL/MAY 2018
Sixth/Seventh Semester
Mechanical Engineering
ME 6603 – FINITE ELEMENT ANALYSIS
(Regulations 2013)

(Common to Mechanical Engineering (Sandwich)/Automobile Engineering/ Manufacturing Engineering, Mechanical and Automation Engineering)

Time: Three Hours Maximum: 100 Marks

Answer ALL questions.

PART - A

(10×2=20 Marks)

- 1. Compare the Ritz technique with the nodal approximation technique.
- 2. Differentiate between primary and secondary variables with suitable examples.
- 3. What are the properties of stiffness matrix?
- 4. Write the conduction, convection and thermal load matrices for 1 D heat transfer through a fin.
- 5. Write down the shape functions for a 4 noded quadrilateral element.
- 6. Distinguish between scalar and vector variable problems in 2D.
- 7. Write the Strain Displacement matrix for a 3 noded triangular element.
- 8. Distinguish between plate and shell elements.
- 9. What are the advantages of natural coordinates?
- 10. Derive the Jacobian of transformation for a 1D quadratic element.

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PART - B

(5×13=65 Marks)

11. a) A tapered bar made of steel is suspended vertically with the larger end rigidly clamped and the smaller end acted on by a pull of 10^5 N. The areas at the larger and smaller ends are 80 cm^2 and 20 cm^2 respectively. The length of the bar is 3 m. The bar weighs 0.075 N/cc. Young's modulus of the bar material is $E = 2 \times 10^7$ N/cm². Obtain an approximate expression for the deformation of the rod using Ritz technique. Determine the maximum displacement at the tip of the bar.

(OR)

b) The Governing Equation for one dimensional heat transfer through a fin of length l attached to a hot source as shown in fig. 11 b is given by

$$\frac{d}{dx} \left[-kA \frac{dT}{dx} \right] + hp(T - T\infty) = 0$$

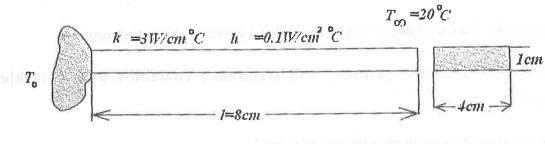
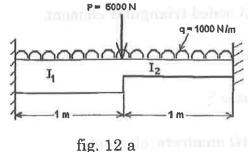


fig. 11 b

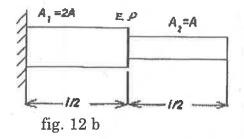
If the free end of the fin is insulated, give the boundary conditions and determine using the Collocation technique the temperature distribution in the fin. Report the temperature at the free end.

12. a) Determine the deflection in the beam, loaded as shown in Fig. 12 a, at the mid-span and at a length of 0.5 m from left support. Determine also the reactions at the fixed ends. E = 200 GPa. $I_1 = 20 \times 10^{-6}$ m⁴, $I_2 = 10 \times 10^{-6}$ m⁴.



(OR)

b) Determine the first two natural frequencies of longitudinal vibration of the stepped steel bar shown in Fig. 12 b and plot the mode shapes. All dimensions are in mm. E = 200 GPa and $\rho = 0.78$ kg/cc. A = 4 cm², length l = 500 mm.



13. a) i) Determine three points on the 50°C contour line for the rectangular element shown the Fig. 13 a. The nodal values are $T_1 = 42$ °C, $T_2 = 54$ °C, $T_3 = 56$ °C and $T_4 = 46$ °C.

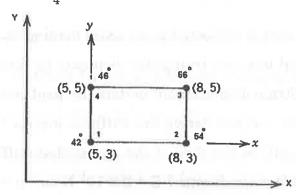


fig. 13 a

ii) Derive the conductance matrix for a 3 noded triangular element whose nodal coordinates are known. The element is to be used for two dimensional heat transfer in a plate fin.

(5)

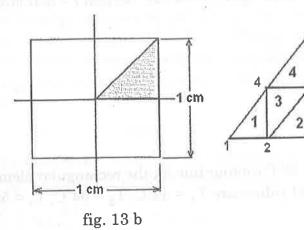
(OR)

b) A square shaft of cross section 1 cm × 1 cm as shown in Fig. 13 b is to be analysed for determining the stress distribution. Considering geometric and boundary condition symmetry 1/8th of the cross section was modeled using four equisized triangular elements as shown. The element stiffness matrix and force vector for a triangle whose nodal coordinates are (0, 0), (0.25, 0) and (0.25, 0.25) are given below. Carry out the assembly and determine the assembled stiffness matrix. Impose the boundary conditions and explain how the unknown stress function values at the nodes can be used to determine the shear stress.

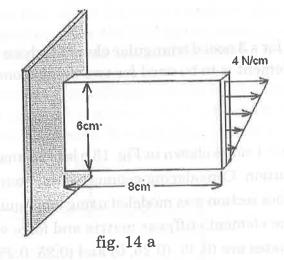
(4)

(6)

Stiffness matrix [K] = $\frac{1}{2}\begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$ Load vector $\{f\} = \begin{cases} 29.1 \\ 29.1 \\ 29.1 \end{cases}$ (13)

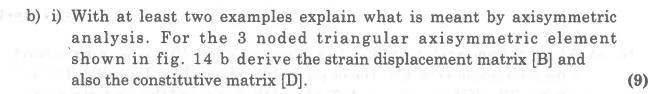


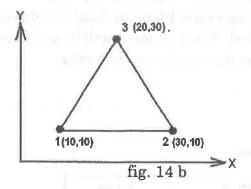
14. a) i) A thin plate of thickness 5 mm is subjected to an axial loading as shown in the Fig. 14 a. It is divided into two triangular elements by dividing it diagonally. Determine the Strain displacement matrix [B], load vector and the constitutive matrix. How will you derive the stiffness matrix? (Need not be determined). What will be the size of the assembled stiffness matrix? What are the boundary conditions? $E = 2 \times 10^7 \text{ N/cm}^2 \mu = 0.3$. (8)



ii) Differentiate between plane stress and plane strain analysis. (5)

(OR)





- ii) Derive the stiffness matrix for a ID linear element.
- 15. a) i) Using Gauss Quadrature evaluate the following integral. (7)

$$I = \int_{-1}^{+1} (4\xi^3 - 2\xi^2 + 3\xi + 6) d\xi$$

ii) Evaluate the shape functions for one corner node and one mid side node of a nine noded quadrilateral element.

(OR)

- b) i) Differentiate between subparametric, isoparametric and superparametric elements. (5)
- ii) For the four noded element shown in Fig. 15. b determine the Jacobian and evaluate its value at the point (0, 0) (8)

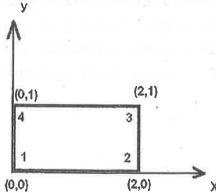


fig. 15 b

PART - C

(1×15=15 Marks)

16. a) A Gantry crane as shown in Fig. 16 a, of overall length 10 m is designed to carry a maximum load of 50 kN. The beam is of I section whose I_{xx} is 40×10^{-6} m⁴. E = 200 GPa. If the maximum deflection of the beam and the support reactions and moments are to be determined using Finite Element Analysis, discuss how the member of length L is to be modeled. What element will be used and what are the boundary conditions? What is the maximum deflection of the beam? (4+4+7)

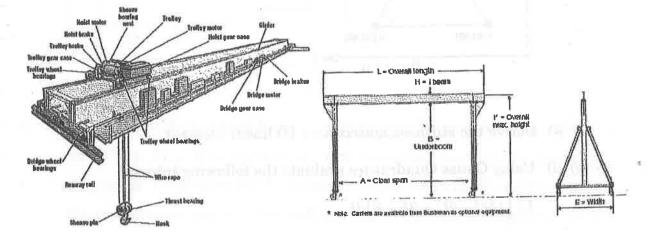


fig. 16 a

$$Stiffness\ Matrix\ [K]^e = \frac{EI}{l^3} \begin{bmatrix} 12 & 6l & -12 & 6l \\ 6l & 4l^2 & -6l & 2l^2 \\ -12 & -6l & 12 & -6l \\ 6l & 2l^2 & -6l & 4l^2 \end{bmatrix} \{f\}^e = \frac{ql}{2} \begin{bmatrix} 1 \\ l/6 \\ 1 \\ -l/6 \end{bmatrix}$$

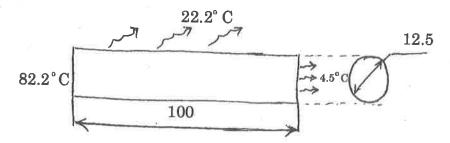
$$\begin{split} N_1 = &1 - \left(\frac{3x^2}{l^2}\right) + \left(\frac{2x^3}{l^3}\right) \\ N_2 = &x - \left(\frac{2x^2}{l}\right) + \left(\frac{x^3}{l^2}\right) \\ N_3 = &\left(\frac{3x^2}{l^2}\right) - \left(\frac{2x^3}{l^3}\right) \\ N_4 = &-\left(\frac{x^2}{l}\right) + \left(\frac{x^3}{l^2}\right) \end{split}$$

$$[M]^{e} = \frac{\rho A l}{420} \begin{bmatrix} 156 & 22l & 54 & -13l \\ 22l & 4l^{2} & 13l & -3l^{2} \\ 54 & 13l & 156 & -22l \\ -13l & -3l^{2} & -22l & 4l^{2} \end{bmatrix}$$

No. of Points	Location	Weight W _i	
1	ξ ₁ = 0.00000	2,00000	
2	$\xi_1, \xi_2 \pm 0.57735$	1.00000	
3	$\xi_1, \xi_3 = \pm \ 0.77459$	0.5555	
	$\xi_2 = 0.00000$	0.88888	

(OR)

b) Consider a cylindrical pin fin as shown in fig. 16 (b) for which $h_{\rm water} = 567 \text{ w/m}^2\text{k}$, $k_{\rm fin} = 207 \text{ w/m.k}$, $h_{\rm air} = 284 \text{ w/m}^2\text{k}$.



The right face of the fin is in contact with water at 4.5°C. The left face of the fin is subjected to a constant temperature of 82.2°C, while the exterior surface of the pin is in contact with moving air at 22.2°C, Using four equal length two node elements to obtain a finite element solution for the temperature distribution across the length of the fin.